



Model M3713SC
3-Phase Power Supply
For 3-Phase Variable Frequency Drives

Customer Reference Manual

Bonitron, Inc.
Nashville, TN



An industry leader in providing solutions for AC drives.

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Bonitron designs and manufactures quality industrial electronics that improve the reliability of processes and variable frequency drives worldwide. With products in numerous industries, and an educated and experienced team of engineers, Bonitron has seen thousands of products engineered since 1962 and welcomes custom applications.

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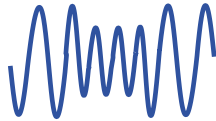
The Bonitron engineering team has the background and expertise necessary to design, develop, and manufacture the quality industrial electronic systems demanded in today's market. A strong academic background supported by continuing education is complemented by many years of hands-on field experience. A clear advantage Bonitron has over many competitors is combined on-site engineering labs and manufacturing facilities, which allows the engineering team to have immediate access to testing and manufacturing. This not only saves time during prototype development, but also is essential to providing only the highest quality products.

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AC DRIVE OPTIONS

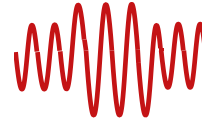
In 1975, Bonitron began working with AC inverter drive specialists at synthetic fiber plants to develop speed control systems that could be interfaced with their plant process computers. Ever since, Bonitron has developed AC drive options that solve application issues associated with modern AC variable frequency drives and aid in reducing drive faults. Below is a sampling of Bonitron's current product offering.

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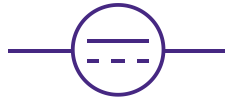
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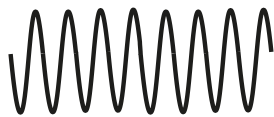
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12 and 18 Pulse Kits



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1. INTRODUCTION

1.1. WHO SHOULD USE

This manual is intended for use by anyone who is responsible for integrating, installing, maintaining, troubleshooting, or using this equipment with any AC drive system.

Please keep this manual for future reference.

1.2. PURPOSE AND SCOPE

This manual is a user's guide for the Model M3713SC 3-phase power supply. It will provide you with the necessary information to successfully install and use the M3713SC modules in your application.

In the event of any conflict between this document and any publication and/or documentation related to the application, the latter shall have precedence.

1.3. MANUAL VERSION AND CHANGE RECORD

Field wiring drawings were updated in Rev 00j.

Drives that cannot be powered updated in Rev 00k.

Voltage ratings and reactors in parallel were updated in Rev 00m.

Voltage ranges were updated in Rev 00n.

Manual template was updated in Rev 01a.

Table 4-1, Section 3.4.1.1, and Section 4.2.5.6 were updated in Rev 01b.

Information regarding 12 and 18 pulse solutions was added in Rev 01c.

Section 7.4 M3713SC with capacitor banks was added in Rev 01d.

Updates were made to Table 6-3 and Figures 3-5 - 3-8, in Rev 01e.

Update made to Table 2-4 in Rev 01f.








Update made to Table 2-4 in Rev 01g.

Update made to section 4.2.5.6 in Rev 01h.

Figure 1-1: Typical M3713SC 3-Phase Power Supply



1.4. SYMBOL CONVENTIONS USED IN THIS MANUAL AND ON EQUIPMENT

	Earth Ground or Protective Earth
	AC Voltage
	DC Voltage
	DANGER: Electrical hazard - Identifies a statement that indicates a shock or electrocution hazard that must be avoided.
	DANGER: Identifies information about practices or circumstances that can lead to personal injury or death, property damage, or economic loss.
	CAUTION: Identifies information about practices or circumstances that can lead to property damage, or economic loss. Attentions help you identify a potential hazard, avoid a hazard, and recognize the consequences.
	CAUTION: Heat or burn hazard - Identifies a statement regarding heat production or a burn hazard that should be avoided.

2. PRODUCT DESCRIPTION

The M3713 is a non-regenerative 3-phase power supply intended for use as the main power supply for a common DC bus drive system. The drives can be either servo or variable frequency drives intended for use in common bus capacitors. The M3713SC has a selectable start-up current limit which is rated at approximately 20% of the full load rating for pre-charging the VFD bus.

2.1. RELATED PRODUCTS

COMMON BUS POWER SUPPLY WITHOUT PRECHARGE

- M3713DM is a 3 phase power supply without precharge.

FUSE PLATE

- M3713F fuse plate provides ready low cost fusing.

DC BUS CAPACITOR

- M3612EC offers capacitors with integral bleeder resistors.

DC BUS SNUBBER

- M3612RC adds extra snubbing to the DC bus for higher frequency bus filtering.

LINE REGEN

- M3645 three phase line regen (30A – 300A)
- M3545 single or three phase line regen (<15A)

BRAKING TRANSISTORS

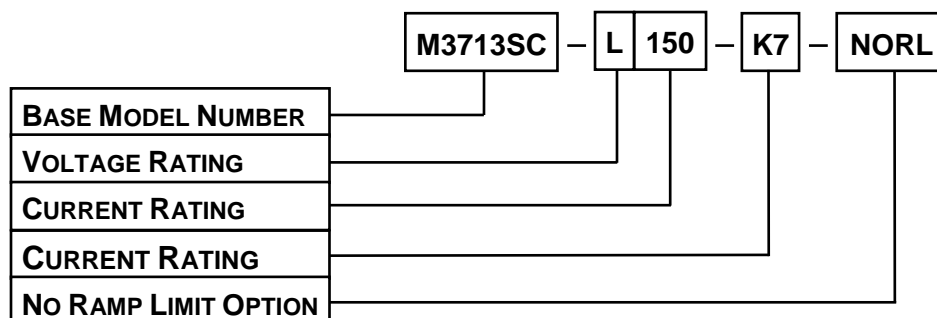
- M3452 heavy duty braking transistor (<1600A)
- M3575T standard duty braking transistor (<600A)
- M3675T low HP braking transistor (<10A)

BRAKING RESISTORS

- M3575R standard duty braking resistors (<30A)
- M3775R various duty load banks (<1600A)

2.2. PART NUMBER BREAKDOWN

Figure 2-1: Example of Part Number Breakdown



BASE MODEL NUMBER

The base model number for the 3-phase power supply with precharge is **M3713SC**.

VOLTAGE RATING

A 1-character code represents the 3-phase AC line input voltage to the M3713SC module. The voltage rating must be selected for the system voltage that will be applied.

Table 2-1: Voltage Rating

RATING CODE	VOLTAGE
L	208 – 240 VAC ±10%
E	380 – 415 VAC ±10%
H	440 - 480VAC ±10%
C	540 – 575 VAC ±10%

CURRENT RATING

A 3-digit code represents the maximum current that the M3713SC is intended to support. Exceeding this limit may cause poor performance and possible failure.

Table 2-2: Current Ratings

RATING CODE	NOMINAL DRIVE CURRENT
030	30 A
075	75 A
150	150 A
225	225 A
375	375 A

CHASSIS CODE

An alphanumeric code represents the chassis style as defined below.

Table 2-3: Chassis Style

CHASSIS CODE	CURRENT	DIMENSIONS (H x W x D)
B5	30-75A	17.75 x 5.50 x 7.80
K7	150-225A	20.00 x 7.12 x 10.35
K10	375A	20.00 x 10.00 x 10.50

NO RAMP LIMIT OPTION

The No Ramp Limit Option is a version of the M3713SC will not have a limit on the precharge time. This option is indicated with the code **NORL**.

2.3. GENERAL SPECIFICATIONS

Table 2-4: General Specifications Chart

PARAMETER	SPECIFICATION
Input Voltage	240VAC, 380VAC, 480VAC, 575VAC, 3Φ, 50 Hz, 60 Hz
Output Voltage DC	Approximately 1.4x Input VAC
Intermittent Duty Limit	150% Full Load Rating for 60 seconds
Precharge Ramp Current Limit	20% Full Load Rating
Overcurrent Limit	175% Full Load Rating
Short Circuit Current Rating (SCCR)	Suitable for use on a circuit capable of delivering not more than 100,000 RMS symmetrical amperes, 575 volts maximum when protected by the recommended fuses
Operating Temp	0°C to +50°C
Storage Temp	-20°C to +65 °C
Humidity	Below 90% Non-condensing
Atmosphere	Free of corrosive gas and conductive dust
Control I/O	Inputs: 24V+ Sinking <ul style="list-style-type: none"> • PRECHARGE ENABLE • RUN ENABLE Outputs: 250VAC, 120mA Max <ul style="list-style-type: none"> • PRECHARGE COMPLETE • READY
Indicators	POWER READY STATUS

2.4. GENERAL PRECAUTIONS AND SAFETY WARNINGS



- HIGH VOLTAGES MAY BE PRESENT!
- NEVER ATTEMPT TO OPERATE OR SERVICE THIS EQUIPMENT WITH ACCESS DOORS OR COVERS OPENED!
- FAILURE TO HEED THESE WARNINGS MAY RESULT IN SERIOUS BODILY INJURY OR DEATH!



- HIGH TEMPERATURES MAY BE GENERATED BY THIS EQUIPMENT DURING NORMAL OPERATION!
- THIS EQUIPMENT SHOULD BE INSTALLED ON A NON-FLAMMABLE SURFACE IN A WELL VENTILATED AREA WITH A MINIMUM OF 2 INCHES OF CLEARANCE ALL AROUND.
- LETHAL VOLTAGES CAN EXIST IN UNIT AFTER POWER HAS BEEN REMOVED. ALLOW 5 MINUTES FOR CAPACITOR BANKS TO DISCHARGE, AND ENSURE THERE ARE LESS THAN 40VDC ON THE DC BUS BEFORE ATTEMPTING SERVICE.
- ALWAYS ALLOW AMPLE TIME FOR THE UNIT TO COOL BEFORE ATTEMPTING SERVICE ON THIS PRODUCT!
- INSTALLATION AND/OR REMOVAL OF THIS PRODUCT SHOULD ONLY BE ACCOMPLISHED BY A QUALIFIED ELECTRICIAN IN ACCORDANCE WITH NATIONAL ELECTRICAL CODE OR EQUIVALENT REGULATIONS.

ANY QUESTIONS AS TO APPLICATION, INSTALLATION, OR SERVICE SAFETY SHOULD BE DIRECTED TO THE EQUIPMENT SUPPLIER.

3. INSTALLATION INSTRUCTIONS



WARNING!

Installation and/or removal of this product should only be performed by a qualified electrician in accordance with National Electrical Code or local codes and regulations.

Proper installation of the power supply modules should be accomplished following the steps outlined below. Be sure to refer to the AC drive instruction manual as these steps are performed. Please direct all installation inquiries that may arise during the installation and startup of this product to the equipment supplier or system integrator.

3.1. ENVIRONMENT

The module should be installed in an area protected from moisture and falling debris. Buildup of dust or debris may cause poor performance and possibly failure. Operating in a wet environment can pose a shock hazard. The recommended temperature range for operating or storing this module is 0°C to +50°C.

3.2. UNPACKING

Upon receipt of this product, please verify that the product received matches the product that was ordered and that there is no obvious physical damage to the unit. If the wrong product was received or the product is damaged in any way, please contact the supplier from which the product was purchased.

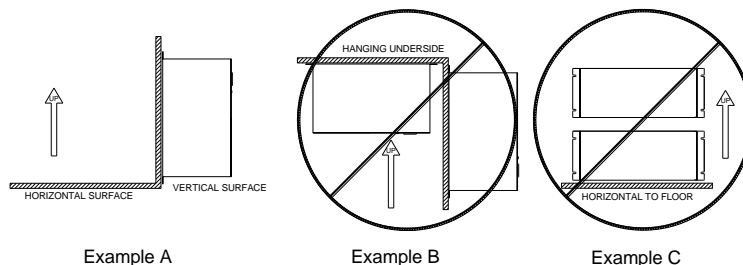
3.3. MOUNTING

3.3.1. MOUNTING THE M3713SC 3-PHASE POWER SUPPLY

The installation site for the module should be chosen with several considerations in mind:

- The unit requires a minimum clearance of two (2) inches in all directions when mounted near a non-heat source.
- Unit should not be exposed to falling debris or condensation.
- The M3713SC must be properly oriented for proper heat flow through the units. The M3713SC must be mounted with the rear surface of the unit to the mounting surface. **Unit should be mounted vertically** as shown in Example A of Figure 3-1.
- **Do Not** mount the unit upside-down or on the underside of a mounting surface as shown in Example B of Figure 3-1.
- **Do Not** mount unit in a horizontal position with its side parallel to the mounting surface or floor as shown in Example C of Figure 3-1.

Figure 3-1: M3713SC Mounting Orientation



3.4. WIRING AND CUSTOMER CONNECTIONS

Be sure to review all AC drive and system documentation for attached equipment as well as the information listed below before proceeding. Connection points and terminal numbers of the AC drive will be found in the documentation provided with those units. See Table 3-1 and Figure 3-2 for connection details.

Use copper conductors rated 75°C.

3.4.1. POWER WIRING



Only qualified electricians should perform and maintain the interconnection wiring of this product. All wiring should be done in accordance with local codes.



This unit contains substantial capacitance and can maintain lethal voltages for a long time after power is removed! Ensure that the DC bus level has dropped below 40VDC before attempting to work on or with this unit!

Table 3-1: Power Connection Specifications

MODEL	CONNECTOR WIRE SIZE RANGE ⁽¹⁾⁽²⁾	TORQUE
L030 E030 H030 C030	6 - 20 AWG	13-16 lb-in
L075 E075 H075 C075	2 - 14 AWG	35-50 lb-in
L150 E150 H150 C150	2/0 - 14CU / 8AL	120 lb-in
L225 E225 H225 C225	350 kcmil - 6 AWG	275 lb-in
L375 E375 H375 C375	500 kcmil - 6 AWG	500 lb-in

⁽¹⁾ Maximum and minimum are the sizes that the terminal block will accept. These are not sizing recommendations.

⁽²⁾ Use copper conductors rated for 75°C.

3.4.1.1. MAIN AC INPUT



When operating this unit with generator, verify the generator is properly sized for required load. The generator may slow down when the drive is precharged and running at full load.

The AC input should be connected to a 3-phase source following the typical guidelines used when sizing for an inverter. Refer to the chart in Section 6.1 for guidance in conducting and overcurrent protection sizing. The input is not sensitive to phase rotation. The unit will operate properly if the phasing is ABC or ACB.

Many installations will need to use an input reactor to reduce the AC input currents as well as the DC bus ripple. Bonitron recommends at least 3% source impedance. If your source transformer is very large compared to the input rating of the power supply, you may need to provide an input reactor.

Reactors **"MUST"** be installed when using parallel power supplies. Do not parallel power supplies with different current ratings.

Refer to the Application Notes in Section 7 for more information on input impedance.

3.4.1.2. OUTPUT TO VFD

DC— and DC+ should be connected to the DC bus terminals of the VFD respectively. Ensure the polarity of the connection is correct, as this can cause severe damage to the drive. Refer to your drive manual for the exact location of this connection.

This link should be fused in accordance with the drive manufacturer's recommendations. If the M3713SC is installed in the same cabinet as the VFD, DC link fusing may not be necessary. Semiconductor fuses such as the A70Q or FWP are recommended for this purpose.



*This power supply does not contain filter capacitance!
Filter capacitors must be integrated into the drive or installed separately.
See Application Notes in Section 7 for assistance.*

It is usually not necessary to attach AC power to the attached drive. Refer to your drive manual for more information.

Do not connect the output of the M3713SC to the braking terminals of the drive. This can also cause severe damage to the drive.

3.4.1.3. GROUNDING CONSIDERATIONS

Using the ground stud provided, ground the chassis in accordance with local codes. Typically, the wire gauge will be the same as is used to ground the attached drive.

Refer to your local codes and standards for installation guidelines.

3.4.2. I/O WIRING**Table 3-2: I/O Wiring Specifications**

TERMINAL	FUNCTION	ELECTRICAL SPECIFICATIONS	MIN WIRE AWG	MAX WIRE AWG	TORQUE LB-IN
TB2-1	NC				
TB2-2&3	PRECHARGE COMPLETE	250VAC / 120mA max	26	16	4.5 lb-in
TB2-4&5	READY	250VAC / 120mA max	26	16	4.5 lb-in
TB2-6	24V	(24V, 100mA)	26	16	4.5 lb-in
TB2-7	PRECHARGE ENABLE	(24V, 100mA)	26	16	4.5 lb-in
TB2-8	24V	(24V, 100mA)	26	16	4.5 lb-in
TB2-9	RUN ENABLE	(24V, 100mA)	26	16	4.5 lb-in
TB2-10	COM	(24V, 100mA)	26	16	4.5 lb-in

3.5. TYPICAL CONFIGURATIONS

Figure 3-2: M3713SC 3-Phase Power Supply Field Wiring Diagram (Single VFD)

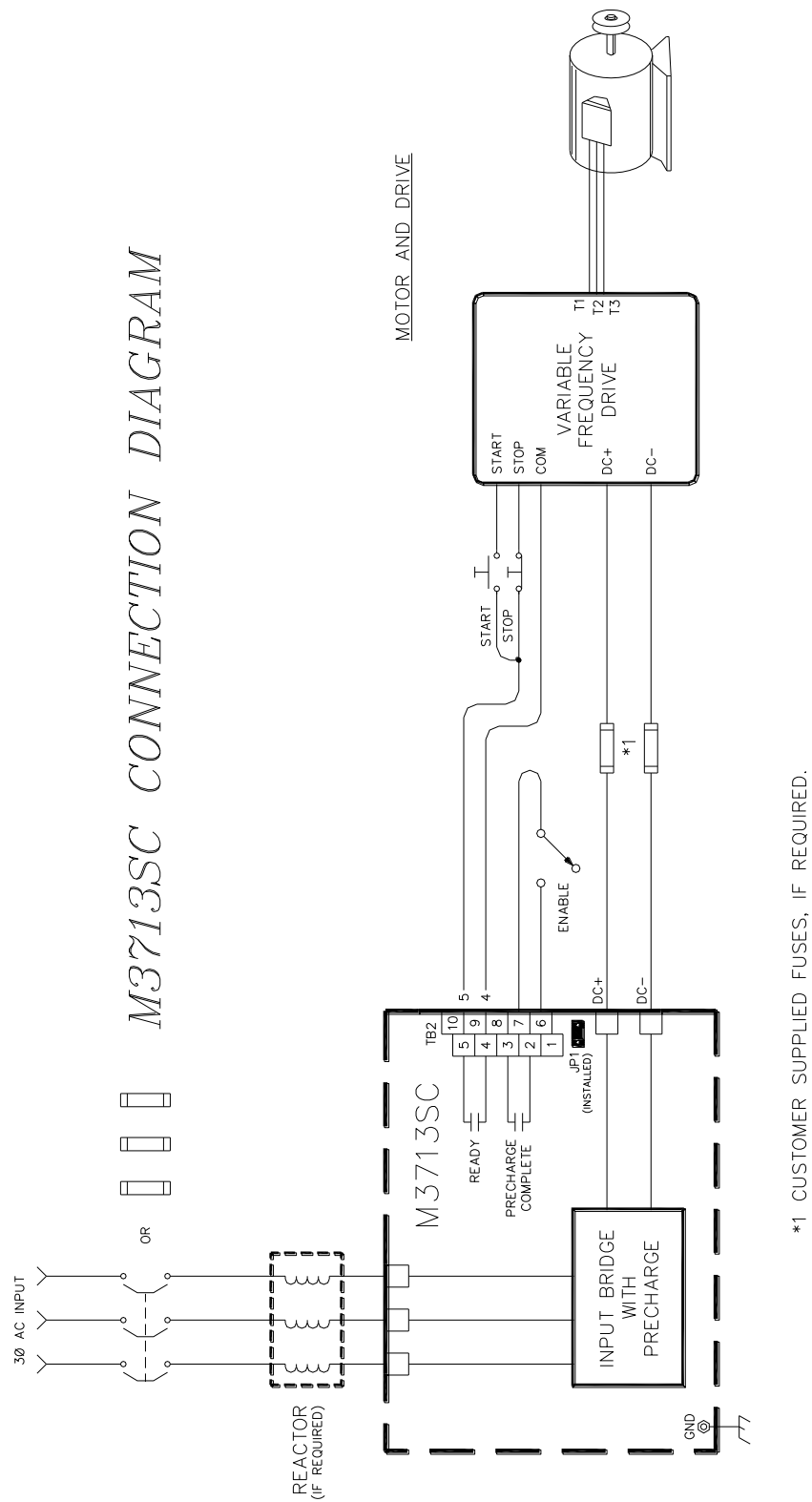


Figure 3-3: M3713SC 3-Phase Power Supply Field Wiring Diagram (Multiple VFD)

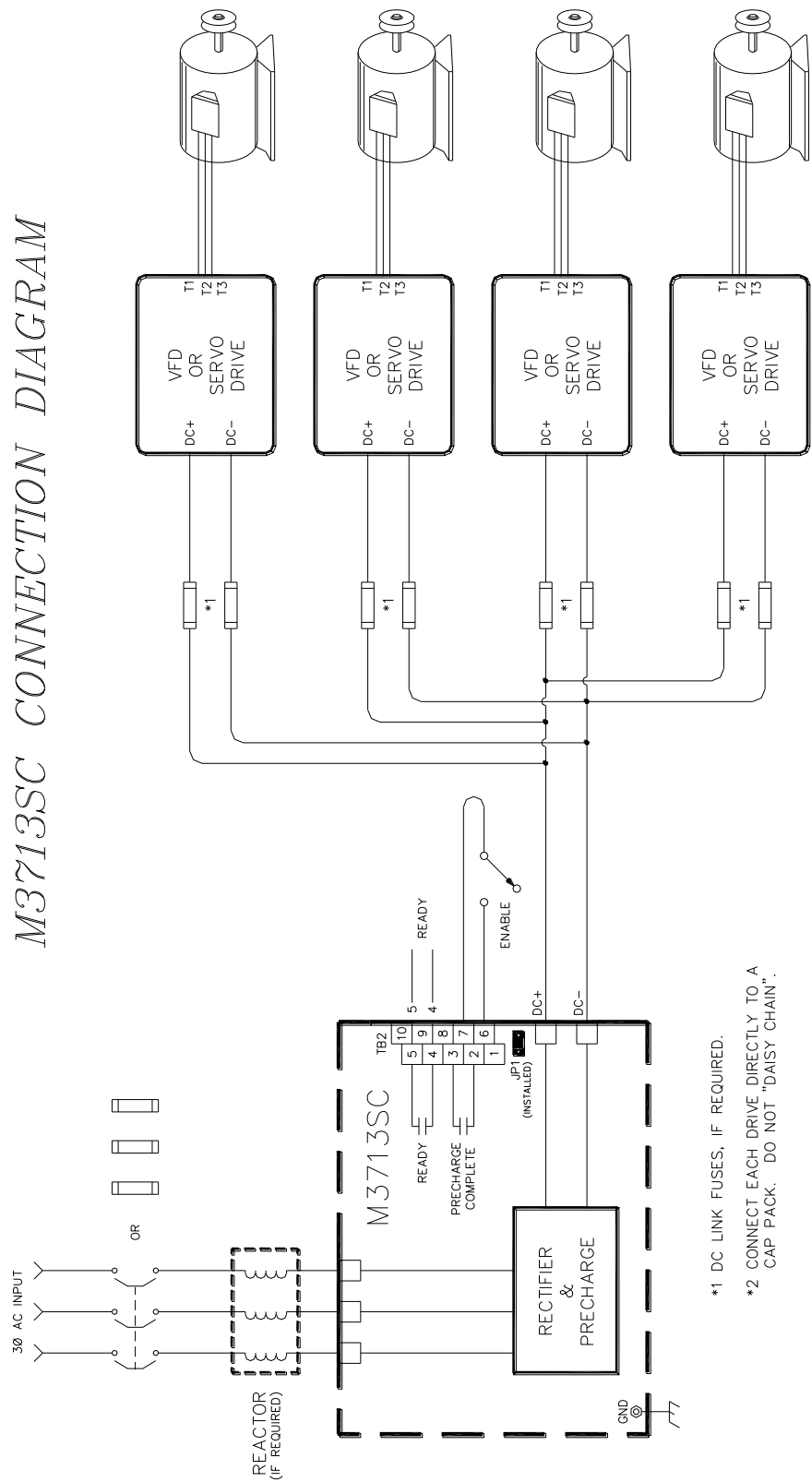
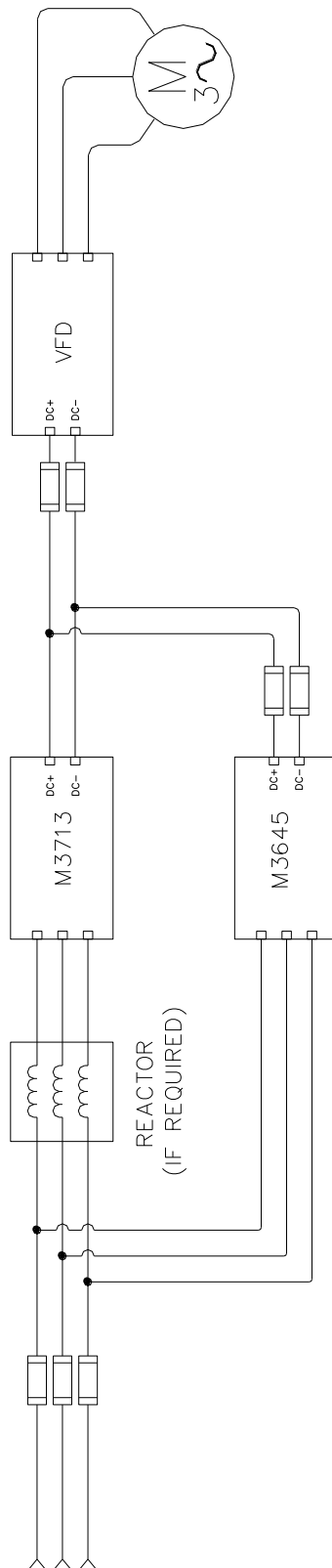


Figure 3-4: M3713SC 3-Phase Power Supply Field with M3645 Regen Wiring Diagram



3.6. TYPICAL 12 PULSE CONFIGURATIONS

Figure 3-5: M3713SC 12-Pulse System

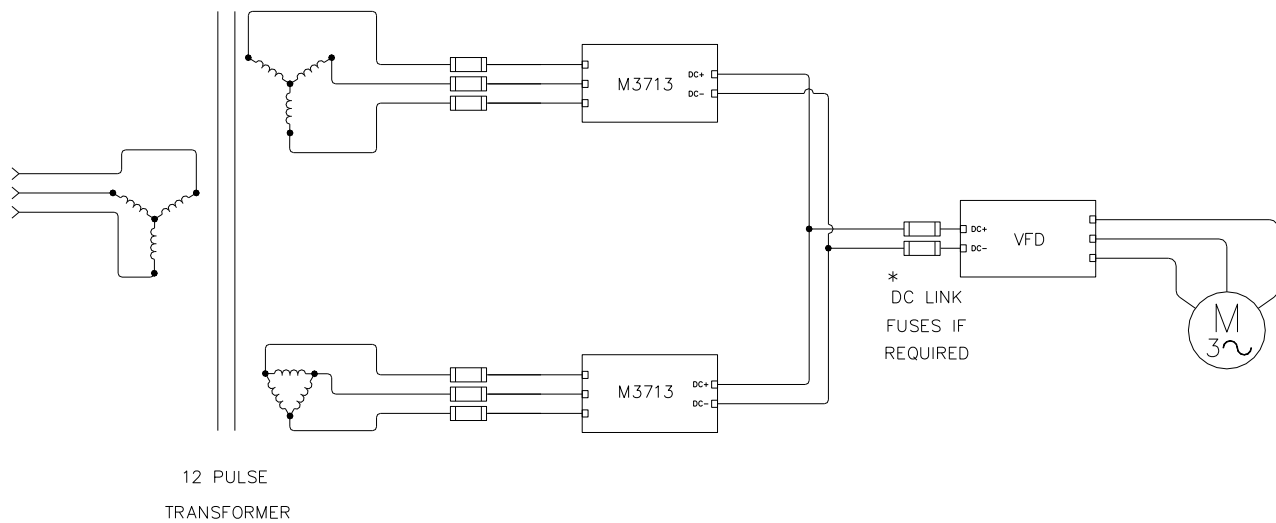
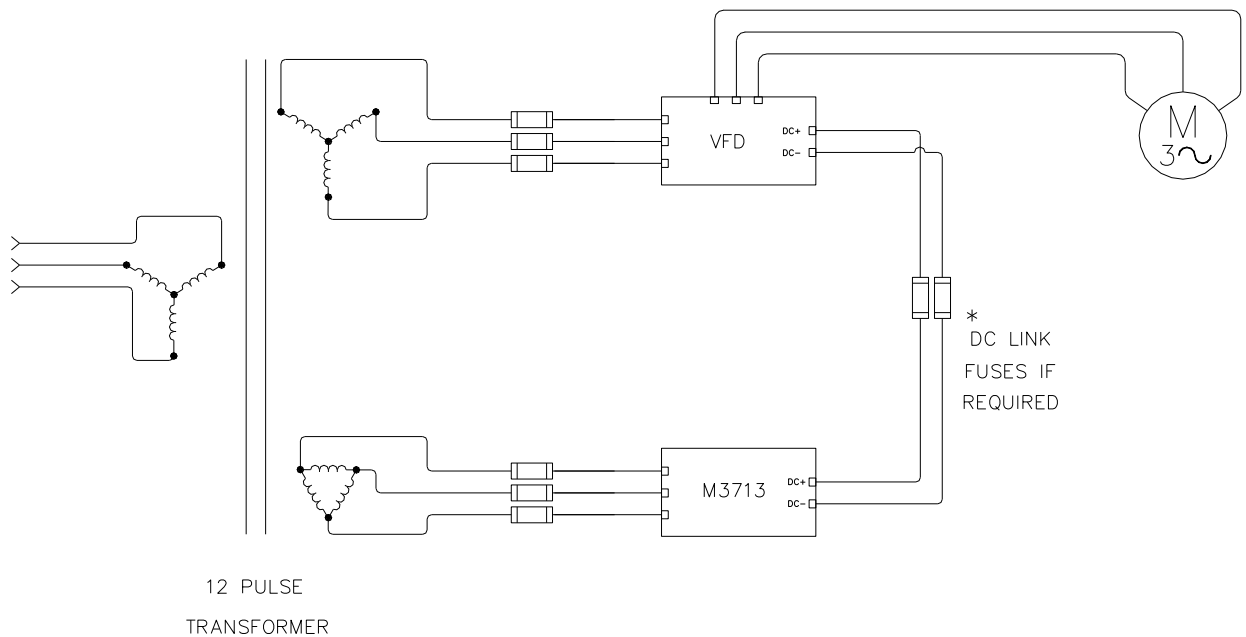


Figure 3-6: M3713SC 12-Pulse System with VFD



3.7. TYPICAL 18 PULSE CONFIGURATIONS

Figure 3-7: M3713SC 18-Pulse System

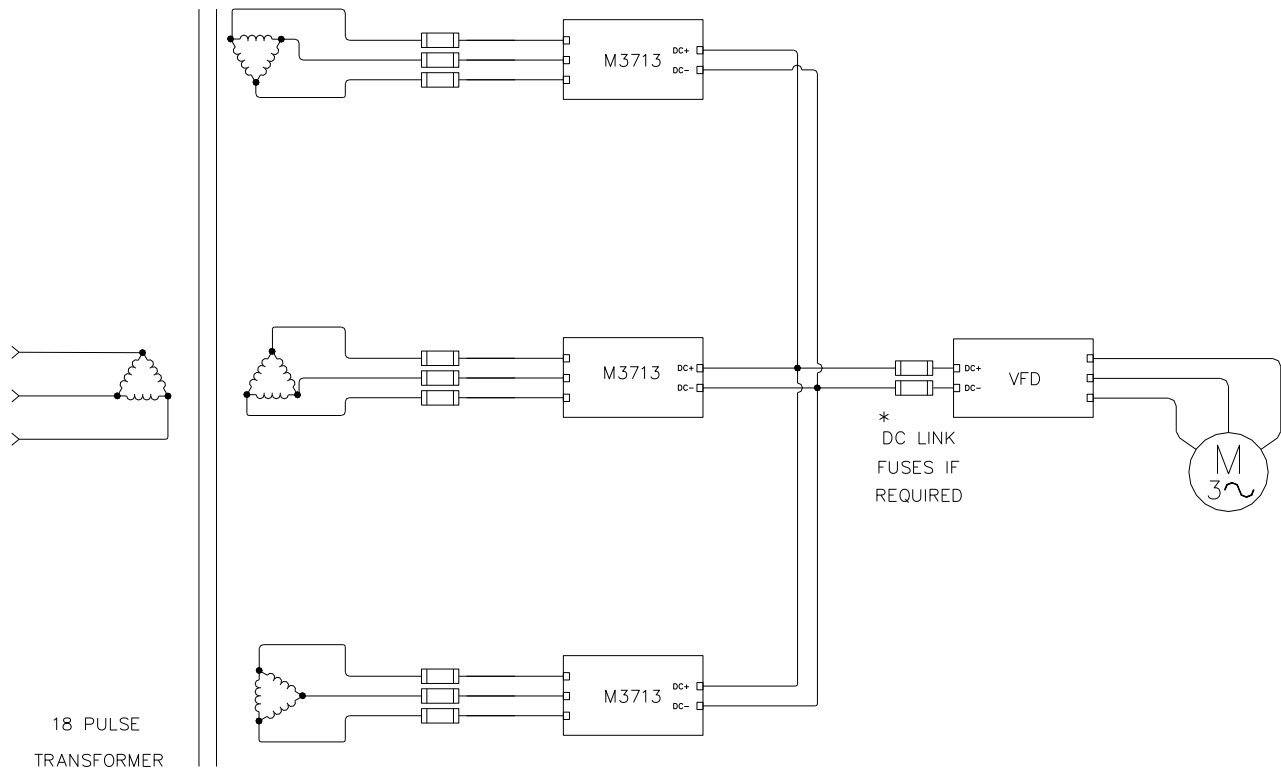
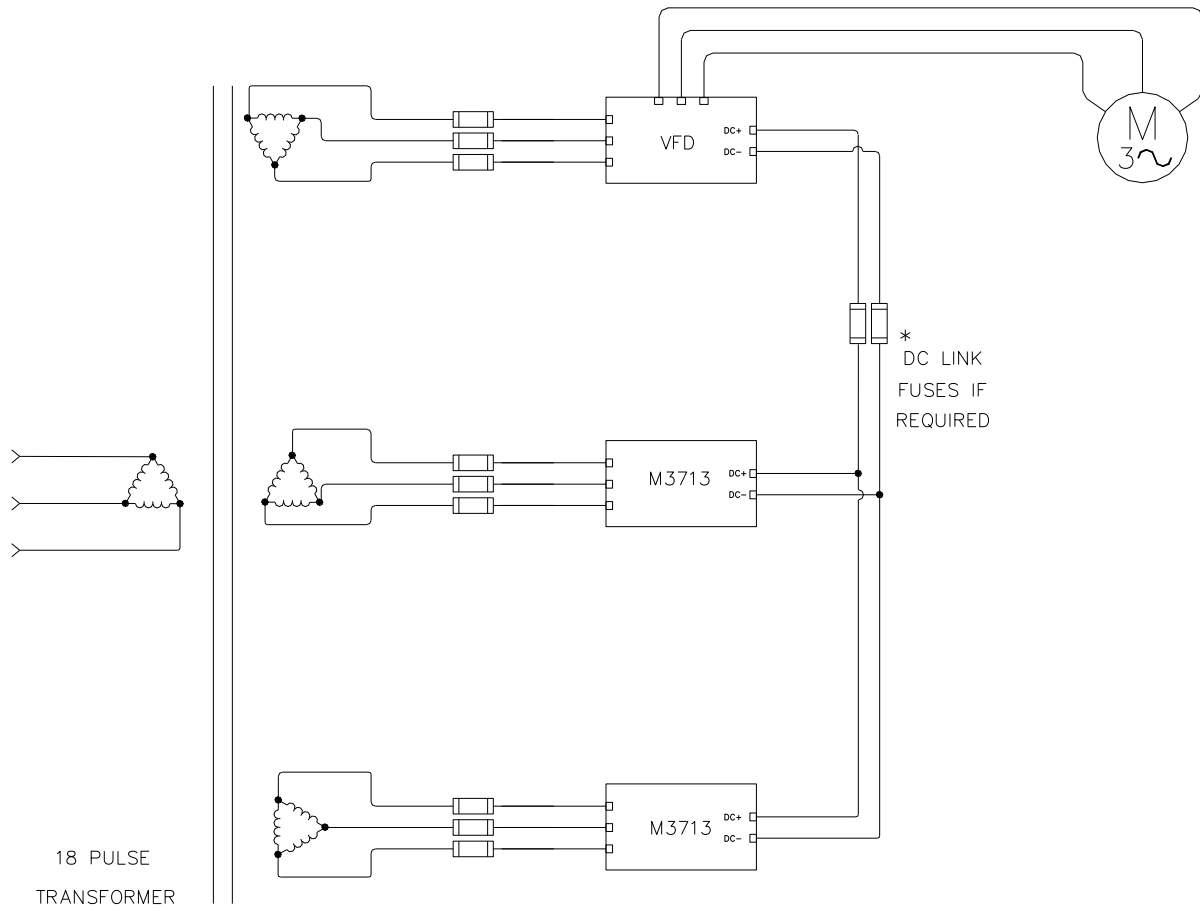


Figure 3-8: M3713SC 18-Pulse System with VFD



4. OPERATION

4.1. FUNCTIONAL DESCRIPTION

The M3713SC 3-phase power supply uses an SCR bridge with phase control to provide DC voltage. These supplies may be used as common bus supplies for multiple drives and inverters.

They can also be used in parallel configurations, such as in 12 or 18 pulse bridge systems. See Section 4.3.2 for further information on interconnecting parallel units.

A complete system will require the M3713SC power supply, bulk bus filtering capacitors, inverters or drives, and any common braking or filtering systems required for the application.

4.1.1. PRECHARGE

The M3713SC DC bus supply has a precharge function that slowly ramps the capacitor bank to full voltage before going into full operation to minimize the inrush currents during bus charging. This function is an automatic current controlled ramp that allows the unit to go into full conduction as soon as the full voltage is sensed on the output.

If the unit cannot charge the output, the unit will not go into operation and a fault will be shown.

4.1.2. OPERATION

During operation, the unit will sense the output for several parameters, including undervoltage, overcurrent, overtemperature and other operational faults. If a fault is sensed, the unit will shut down the DC output, and the fault code will be displayed on the front panel of the unit.

4.2. FEATURES

4.2.1. I/O – INPUTS AND OUTPUTS

4.2.1.1. TB2-2&3 PRECHARGE COMPLETE CONTACTS

The PRECHARGE Complete contacts will close when the unit has completed precharging.

This output can be used in configurations to stage multiple power supplies are used in parallel.

Please refer to the Application Notes for further information on interconnecting parallel units.

4.2.1.2. TB2-4&5 READY CONTACTS

The READY contacts will close when the unit is ready to operate at full capacity. This contact will close after the precharge is complete, and the RUN ENABLE input is on.

The READY output will open on any fault.

The attached drive system should not be started until the READY contacts close.

4.2.1.3. TB2-7 PRECHARGE ENABLE INPUT

A +24VDC signal will enable the unit for precharge. These inputs are isolated so they may be interfaced with PLC or external switch.

Once the contact is closed, the unit will ramp the voltage to the maximum output in approximately 2½ seconds in order to precharge the bus capacitance. If the current during this ramp exceeds the current limit, the ramp will take longer. See Section 5.3.3.1 for details on setting this limit.

If the precharge sequence takes longer than 5 seconds, the unit will stop precharging and go into a fault mode unless that unit has the No Ramp Limit Option.

If the Enable input is left open, the unit will remain in standby.

Once this input goes off, all faults but phase loss are cleared, and the unit can be enabled again to continue operation.

4.2.1.4. TB2-9 RUN INPUT

The second enable is used when there is more than one unit connected to each other. Once the PRECHARGE Complete output comes on, the RUN Input will need a +24VDC input within 6 seconds to continue operation. If the RUN Input does not go high, the unit will go into a fault mode and the DC output will go to zero.

If the unit is not used in a multiple configuration, this input can be effectively disabled by placing JP1 on the circuit board, or by placing a jumper between TB2-8 and TB2-9.

4.2.1.5. TB2-10 COMMON

This is the common for the inputs, and can be used if the inputs are to be driven by an external power source. This common must be connected to the common of the external power source for the inputs to operate.

4.2.2. JUMPERS**4.2.2.1. JP1 – STAND ALONE OPERATION**

JP1 is used to disable the function of the RUN Input, described in Section 4.2.1.4. When this jumper is installed, the RUN Input is held high, and when the unit finishes precharge, will go immediately into full conduction operation.

This jumper can also be installed if parallel units are not used in a cascade configuration.

Figure 4-1: K7 and K10 Chassis Jumper 1 Location

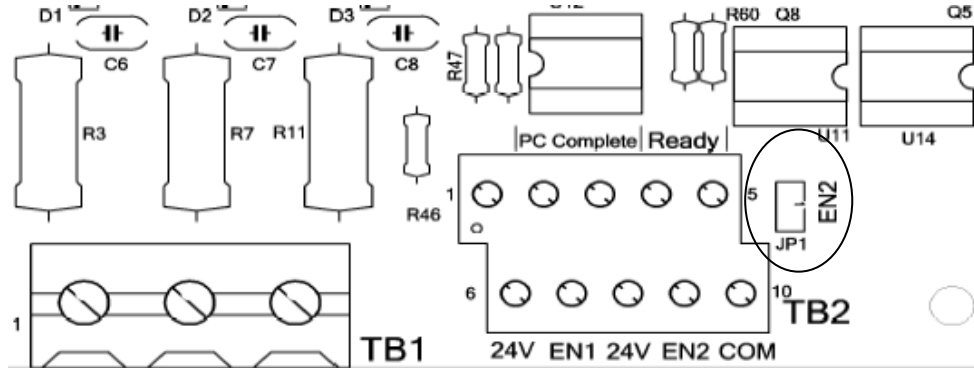
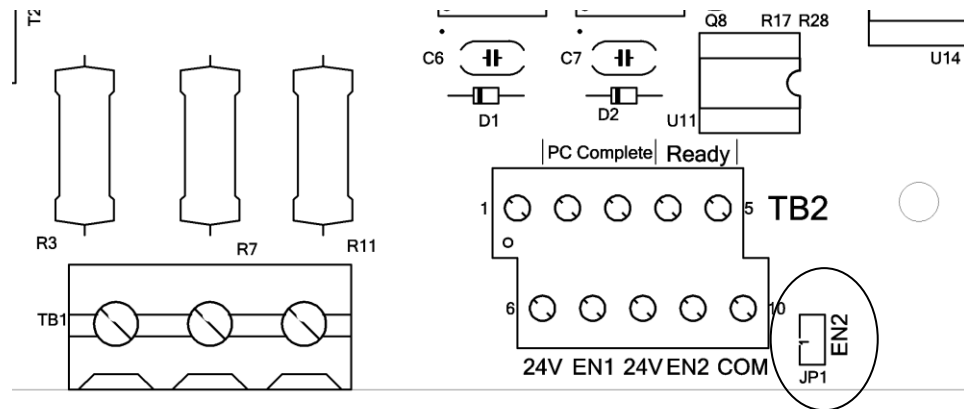


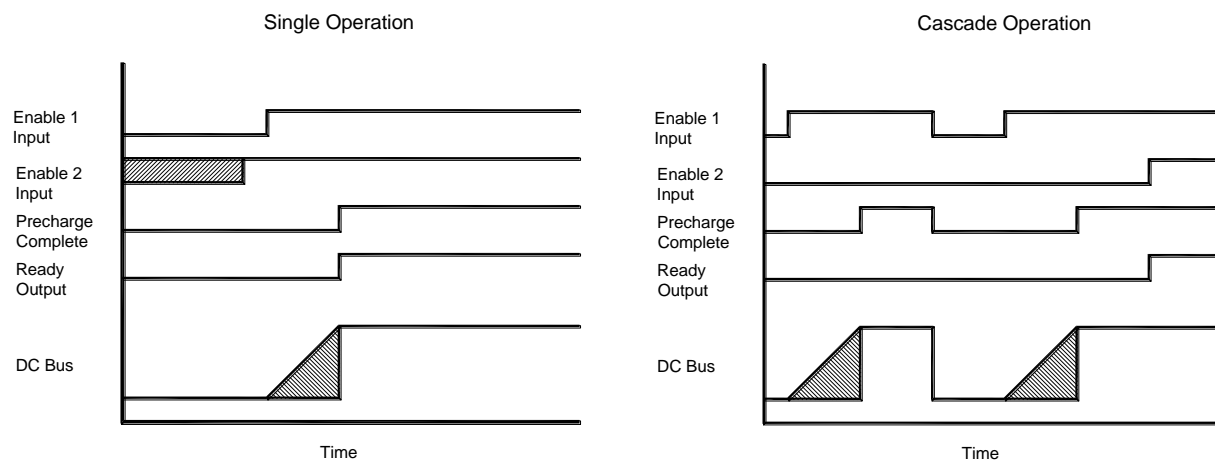
Figure 4-2: B5 Chassis Jumper 1 Location



4.2.3. TIMING CHART

The timing charts in Figure 4-3 show the typical modes of operation.

Figure 4-3: Typical Modes of Operation



4.2.4. EXTERNAL INDICATORS

The unit has indicators in the front panel that will show basic status information for the supply and can be used for troubleshooting or general information.

4.2.4.1. POWER

The POWER indicator on the front of the unit will be illuminated when control power is applied to the bridge and the processor is functioning properly.

4.2.4.2. READY

The Ready indicator illuminates when the unit has power applied and is ready to operate.

When the Enable input is activated, the indicator will be flashing during the precharge portion of operation.

When the unit is done pre-charging, this indicator will be solid, and the Ready contact will close.

4.2.4.3. STATUS INDICATOR

The Status indicator illuminates when there is a fault active in the unit. When this indicator is on, the Ready contact will open, and the unit will not supply power to the VFD.

If there are no faults, this indicator will be off.

The blink sequence will indicate the specific fault. See Table 4-1 for more information on the sequence of flashes.

4.2.5. FAULT MODES

When the unit is in a fault, there is no output from the converter, and the power supply shuts down. All faults are cleared by powering the unit down and restarting, or by toggling the PRECHARGE ENABLE input. When the PRECHARGE ENABLE input is low, the blink code will continue to show the condition of the last fault.

See Troubleshooting in Section 5 for further assistance on any of the following alarms.

Table 4-1: Blink Patterns

BLINK PATTERN	FAULT CONDITION
Fast Blink	Precharging
Off	No Fault
On	Missing Run Input
On – Off	Ramp Limit
On – On – Off	Overcurrent
On – On – On – Off	Overtemperature
On – On – On – On – Off	Undervoltage
On – On – On – On – On- Off	Phase Loss
On – On – On – On – On – On - Off	Frequency Loss

4.2.5.1. PRECHARGING

When the unit is precharging the output, the Status Input will flash rapidly. This does not indicate a fault, but does indicate that the unit has a PRECHARGE ENABLE input and the ramp has not completed.

Once the unit goes through precharge successfully, the unit will go into full conduction, and the Status light should go off.

If the unit does not go through precharge successfully, the unit will indicate one of the faults listed below.

4.2.5.2. MISSING RUN INPUT

When precharging is complete, unit must see the Run Input within six seconds. If the Run Input does not go high, the unit will shut down.

4.2.5.3. RAMP LIMIT

If the unit tries to precharge for more than 5 seconds without reaching the full output voltage, the unit will go into a Ramp Limit fault. This indicates that the unit was unable to precharge the load.

This fault is reset on power down, or when the ENABLE input is removed.

If the unit has the NORL option then the unit does not have a ramp limit and this fault will not occur.

4.2.5.4. OVERCURRENT

If there is a sustained current demand over 175% of the units rated current output, the unit will shut down.

Do not use this fault as a substitute for circuit overcurrent protection. Fuses or circuit breakers should be installed in accordance with local codes and regulations.

This fault is reset on power down, or when the ENABLE input is removed.

4.2.5.5. OVERTEMPERATURE

This indicates that the unit's heatsink has exceeded 160°F. The unit will shut down and the fault will not reset until the heatsink cools.

Once the unit cools, the fault can be reset on power down, or when the ENABLE input is removed.

4.2.5.6. UNDERVOLTAGE

After the unit is precharged, the output voltage is monitored. If the output voltage drops below 80% of the nominal output voltage, the unit will generate an undervoltage fault. This can indicate a problem with either the input voltage or a hookup problem. See Troubleshooting in Section 5.3 for further assistance.

This fault is reset on power down, or when the ENABLE input is removed.

4.2.5.7. PHASE LOSS

The unit must have input power to all phases to operate correctly. The unit does not need a specific phase rotation, but the loss of a phase will cause the unit to shut down. This fault is reset on power down, or when the ENABLE input is removed.

4.2.5.8. FREQUENCY LOSS

This indicates the unit failed to properly detect the frequency of the AC source. This fault latches until the unit is powered down.

4.3. STARTUP

This section covers basic checks and procedures that may be used when performing a startup with a M3713SC.

4.3.1. PRE-POWER CHECKS

- Ensure that all connections are tight and that all wiring is of the proper size and rating for operation.
- Verify continuity of all input fuses.
- Ensure that the polarity of the DC link to the attached drive is correct.
- Check for exposed conductors that may lead to inadvertent contact.
- Check for any debris, shavings, trimmings, etc. that may cause shorts or obstruct ventilation on unit.
- Perform the pre-power checks required for the attached drive.

4.3.2. STARTUP PROCEDURE AND CHECKS

4.3.2.1. SINGLE MODULE OPERATION

- For single mode operation, JP1 should be installed, or the Run Enable input should be jumpered high. See Section 4.2.2.1 for more information.
- After completing pre-checks and the recommended checks for the connected equipment, apply power to the system.
- The POWER indicator on the front panel will illuminate.
- Close the contact on the PRECHARGE ENABLE input.
- The STATUS indicator will flash rapidly during precharge.
- Once PRECHARGE is complete, the Ready indicator will stay on solid, and the Ready contacts will close.
- The attached drive should then be started up according to its instructions.

4.3.2.2. PARALLEL MODE OPERATION

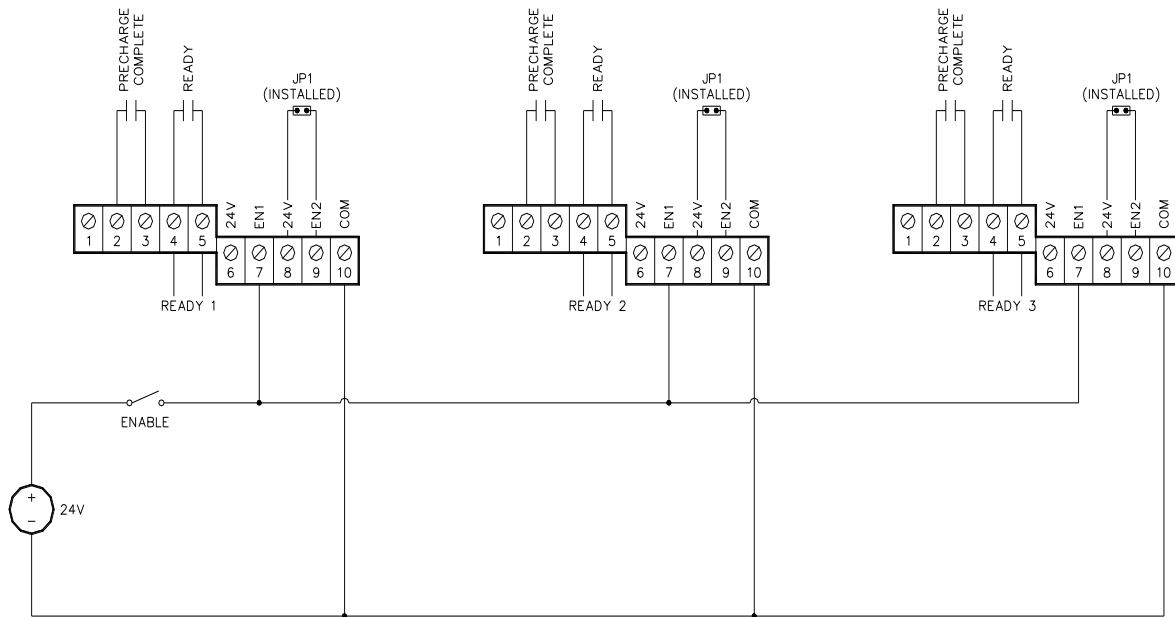
Parallel mode can be used when the system can have all of the units pre-charging at once. In this case, the PRECHARGE ENABLE is wired to all of the units in parallel, and all units will start at once. In this mode, all units can be jumpered to ignore the Run Enable input.

An example of this wiring is shown in Figure 4-4.

A fault on one unit will not affect the operation of the others, and the individual Ready contacts can be monitored remotely to de-rate or stop the system output as required.

- After completing pre-checks and recommended checks for connected equipment, apply power to the system.
- The POWER indicator on the front panels will illuminate.
- Close the contact on the PRECHARGE ENABLE inputs.
- The STATUS indicator will flash rapidly during precharge.
- Once PRECHARGE is complete, the Ready indicators will stay on solid, and the Ready contacts will close.
- The attached drive should then be started up according to its instructions.

Figure 4-4: Parallel Mode Interconnection



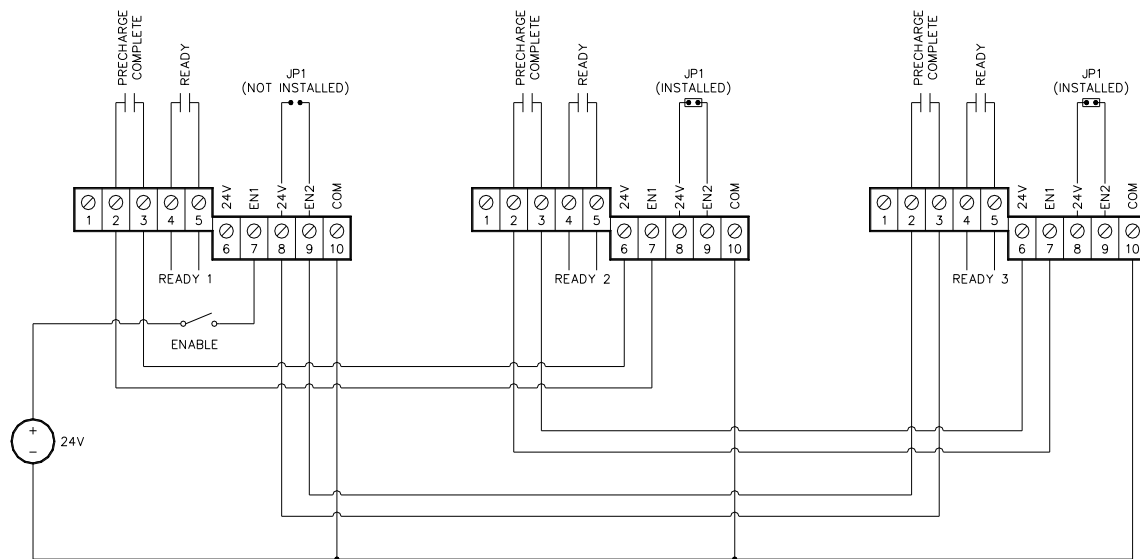
4.3.2.3. CASCADE MODE OPERATION

Cascade mode can be used to allow an interconnection of multiple power supplies to disable all other power supplies in the event of an individual fault.

The system ENABLE is wired to the first power supply in the system and the rest are daisy chained using the PRECHARGE Complete output.

An example of this wiring is shown in Figure 4-5.

- After completing pre-checks and the recommended checks for the connected equipment, you may apply power to the system.
- The POWER indicator on the front panels should illuminate.
- Close the contact on the PRECHARGE ENABLE input to the first unit.
- The STATUS indicator will flash rapidly during precharge.
- Once PRECHARGE is complete, the first unit will enable the precharge for the next unit in the chain. The next unit's STATUS indicator should flash briefly and likewise with the other units in the chain.
- Once all units have gone through the precharge cycle, the last unit will enable the RUN ENABLE input on the first unit in the chain, and the signal will cascade down through the other units.
- READY indicators should stay on solid, and the READY contacts will close.
- The attached drive should then be started up according to its instructions.
- In the event of a single power supply fault, all the units will be disabled, and fault codes will be displayed on the faulted units. The unit that initiated the fault will have a fault code different from Missing Run Input.

Figure 4-5: Cascade Mode Interconnection

5. MAINTENANCE AND TROUBLESHOOTING

Repairs or modifications to this equipment are to be performed by Bonitron approved personnel only. Any repair or modification to this equipment by personnel not approved by Bonitron will void any warranty remaining on this unit.

5.1. PERIODIC TESTING

There are no requirements for periodic testing of these units. When performing routine maintenance it may be beneficial to repeat start-up procedures and checks.

5.2. MAINTENANCE ITEMS

Check periodically for debris, clear as necessary. Buildup can cause short circuits and dangerous conditions.

Reduced airflow can cause nuisance tripping and overheating.

Power should not be applied when blowing dust and debris out of unit.

5.3. TROUBLESHOOTING



This unit contains substantial capacitance and can maintain lethal voltages for a long time after power is removed! Ensure that the DC bus level has dropped below 40VDC before attempting to work on or with this unit!



Only qualified personnel familiar with adjustable frequency AC drives and associated machinery should plan or implement the installation, start-up and subsequent maintenance of the system. Failure to comply may result in personal injury, death and/or equipment damage!

Feel free to call Bonitron at any time the equipment appears to be having problems.

5.3.1. POWER INDICATOR IS NOT ON

- Check AC input voltage at TB1 terminals 1, 2 and 3. This voltage should be the same as the system voltage for the unit, either 240VAC for L units, 480VAC for H units or 575VAC for C units.
- If there is voltage at these terminals, and the POWER indicator is not on, the unit may be damaged, and need repair. Contact your supplier or Bonitron for assistance.

5.3.2. ATTACHED DRIVE DOES NOT COME ON

- If the POWER Indicator is on, make sure the ENABLE inputs are activated by closing a contact between TB2 6 and 7 to enable the precharge and between TB2 8 and 9 to enable the unit with either a switch or jumper.
- The STATUS indicator should begin to flash rapidly, or come on solid.
- If the STATUS indicator does not flash or come on solid, then check the connection to the Enable Input.
- If the READY indicator comes on solid, check the connections between the M3713SC and the attached drive. If there are fuses in the link, make sure they are not blown.
- If the READY indicator does not come on solid, continue troubleshooting below.

5.3.3. STATUS INDICATOR FLASHES

Check the blink codes listed in Table 4-1 for the specific fault indicated. Once a fault is sensed, the STATUS indicator will continue to flash the fault code until the unit is powered down, or the PRECHARGE ENABLE input is toggled off and then back on.

5.3.3.1. RAMP LIMIT

Ramp Limit occurs when the unit is unable to precharge the output within 5 seconds. The input ramp current limit is factory set to 20% of the output rating of the unit. This is usually sufficient to precharge any attached load. If it is not, this can indicate one of the following:

1. The attached drive exceeds the ratings of the M3713SC.
2. The attached drive is already enabled and loaded.
3. The drive may have a large capacitor bank.
4. The wiring may be faulty between the drive and the M3713SC.

Follow these steps to try to determine the problem:

- Power down the unit and check the wiring thoroughly to make sure there are no faulty connections or shorts between the drive and the M3713SC.
- Ensure that the drive is not enabled or started during precharge. One way to ensure this is to use the READY contact in the start/stop string of the drive's control input.
- Check the DC bus voltage during precharge. If the voltage rises during the precharge sequence, make sure the M3713SC unit is rated for the drive attached.

5.3.3.2. OVERCURRENT

If there is a sustained current demand over 175% of the unit's rated current output, the unit will shut down.

Do not use this fault as a substitute for circuit overcurrent protection. Fuses or circuit breakers should be installed in accordance with local codes and regulations.

This fault is reset on power down, or when the ENABLE input is toggled off and back on.

- Power down the unit and check the wiring thoroughly to make sure there are no faulty connections or shorts between the drive and the M3713SC.
- Enable the unit and measure the current during operation and ensure it does not exceed the rating of the power supply.
- If the fault reappears, make sure the M3713SC unit is rated for the drive attached. If so, there may be an issue with the attached drive.

5.3.3.3. OVERTEMPERATURE

This indicates that the unit's heatsink has exceeded 70°C (160°F). The unit will shut down until the heatsink cools.

Once the unit cools, the fault can be reset on power down, or when the ENABLE input is removed.

If the unit frequently overheats, it may be overloaded. The M3713SC is designed for 150% of rated output current for 60 seconds at a maximum of 40°C (104°F). If the ambient temperature around the M3713SC is higher than this, the unit must be de-rated.

Ensure that the fan is running when the unit is hot. The fan will start running when the heatsink reaches 45°C (110°F).

5.3.3.4. UNDERVOLTAGE

This indicates the output DC voltage has dropped to a level insufficient to continue operation. If this occurs, monitor the DC bus voltage and the AC input voltage.

Verify that the source voltage is not being reduced too much when the system is loaded, as the input impedance to the power supply may be too high.

See Section 7 for additional information.

5.3.3.5. PHASE LOSS

The unit has phase loss detection that will shut the unit down in case one or more of the input phases is lost because of a fuse or other fault. This is to protect the unit from an unbalanced input.

If you are showing a phase loss, check the main input devices to each incoming leg, such as fuses or circuit breakers.

5.3.3.6. FREQUENCY LOSS

The unit cannot find the frequency of AC source. This fault should only occur directly after the unit is first powered on.

This is a latching fault and power to the M3713SC should be cycled to clear the fault.

If the fault fails to clear check all incoming AC fuses.

5.4. TECHNICAL HELP – BEFORE YOU CALL

If technical help is required, please have the following information when calling:

- Serial number of unit
- Name of original equipment supplier (if available)
- Record the line voltage
- Record the DC bus voltage immediately after the AC voltage
- Brief description of the application
- Drive and motor hp or kW
- kVA rating of power source
- Source configuration and grounding

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6. ENGINEERING DATA

6.1. RATINGS CHARTS

Table 6-1: Three Phase Power Ratings Chart

MODEL NUMBER	SYSTEM VOLTAGE	NOMINAL DRIVE HP	APPROX. 3Ø INPUT CURRENT (AC RMS) ⁽¹⁾	INPUT FUSE SIZE (J-TYPE OR BETTER) ⁽²⁾	OUTPUT CURRENT (DC AVERAGE)
M3713SC-L030-B5	208 – 240VAC	7.5	27	35	30
M3713SC-L075-B5		20	65	80	75
M3713SC-L150-K7		50	134	200	150
M3713SC-L225-K7		75	210	250	225
M3713SC-L375-K10		125	340	400	375
M3713SC-E030-B5	380 - 415VAC	12	27	35	30
M3713SC-E075-B5		32	65	80	75
M3713SC-E150-K7		80	134	200	150
M3713SC-E225-K7		120	210	250	225
M3713SC-E375-K10		200	340	400	375
M3713SC-H030-B5	440 - 480VAC	15	30	35	30
M3713SC-H075-B5		40	75	80	75
M3713SC-H150-K7		100	150	200	150
M3713SC-H225-K7		150	225	250	225
M3713SC-H375-K10		250	375	400	375
M3713SC-C030-B5	540 - 575VAC	20	30	35	30
M3713SC-C075-B5		50	75	80	75
M3713SC-C150-K7		125	150	200	150
M3713SC-C225-K7		175	225	250	225
M3713SC-C375-K10		300	375	400	375

⁽¹⁾ AC Input currents are dependent on source impedance and are listed here only as a guideline.

⁽²⁾ Suitable for use on a circuit capable of delivering not more than 100,000 RMS symmetrical amperes, 575 volts maximum when protected by the recommended fuses.

6.2. WATT LOSS

Table 6-2 lists the maximum watt loss generated by the listed units. When installing M3713SC units in an enclosure, consideration should be given to internal temperature rise. The following table is based upon the maximum capability of each unit.

Table 6-2: Full Load Watt Loss

OUTPUT CURRENT	FULL LOAD OF POWER SUPPLY
30 A	150 W
75 A	260 W
150 A	500 W
225 A	800 W
375 A	1150 W

Applications that do not utilize the full capacity may be calculated as follows:

$$\text{Watt Loss} = \text{Full Load Watt Loss} \left(\frac{\text{Average HP}}{\text{Rated HP}} \right)$$

Table 6-3: Reactor Specifications Chart

M3713SC MODEL NUMBER	SYSTEM VOLTAGE	NOMINAL DRIVE HP	BONITRON REACTOR NUMBER	REACTOR INDUCTANCE μ H
M3713SC-L030-B5	208 – 240VAC	7.5	IN RL-03502	800
M3713SC-L075-B5		20	IN RL-08002	400
M3713SC-L150-K7		50	IN RL-13001	100
M3713SC-L225-K7		75	IN RL-20002B14	110
M3713SC-L375-K10		125	IN RL-32002B14	75
M3713SC-E030-B5	380 - 415VAC	12	IN RL-02503	1800
M3713SC-E075-B5		32	IN RL-05503	850
M3713SC-E150-K7		80	IN RL-16003	230
M3713SC-E225-K7		120	IN RL-20003B14	185
M3713SC-E375-K10		200	IN RL-32003B14	125
M3713SC-H030-B5	440 - 480VAC	15	IN RL-02503	1800
M3713SC-H075-B5		40	IN RL-05503	850
M3713SC-H150-K7		100	IN RL-13003	300
M3713SC-H225-K7		150	IN RL-20003B14	185
M3713SC-H375-K10		250	IN RL-32003B14	125
M3713SC-C030-B5	540 - 575VAC	20	IN RL-02503	1800
M3713SC-C075-B5		50	IN RL-05503	850
M3713SC-C150-K7		125	IN RL-13003	300
M3713SC-C225-K7		175	IN RL-20003B14	185
M3713SC-C375-K10		300	IN RL-32003B14	125

6.3. CERTIFICATIONS

All M3713 models are UL and cUL listed by Underwriter's Laboratories under file number E204386 for UL508C Power Conversion Equipment

6.4. DIMENSIONS AND OUTLINES

Table 6-4: Chassis Dimensions for M3713SC Module

MODEL NUMBER	CHX	OVERALL (IN INCHES)			MOUNTING (IN INCHES)		WEIGHT (LBS.)
		HEIGHT	WIDTH	DEPTH	HEIGHT	WIDTH	
M3713SC-L030	B5	17.75	5.50	7.80	16.75	3.0	16.5
M3713SC-E030							
M3713SC-H030							
M3713SC-C030							
M3713SC-L075	B5	17.75	5.50	7.80	16.75	3.0	16.5
M3713SC-E075							
M3713SC-H075							
M3713SC-C075							
M3713SC-L150	K7	20.00	7.12	10.30	19.25	5.0	26.5
M3713SC-E150							
M3713SC-H150							
M3713SC-C150							
M3713SC-L225	K7	20.00	7.12	10.30	19.25	5.0	28.5
M3713SC-E225							
M3713SC-H225							
M3713SC-C225							
M3713SC-L375	K10	20.00	10.00	10.50	19.00	7.0	41.5
M3713SC-E375							
M3713SC-H375							
M3713SC-C375							

Figure 6-1: M3713SC B5 Chassis Dimensional Outline

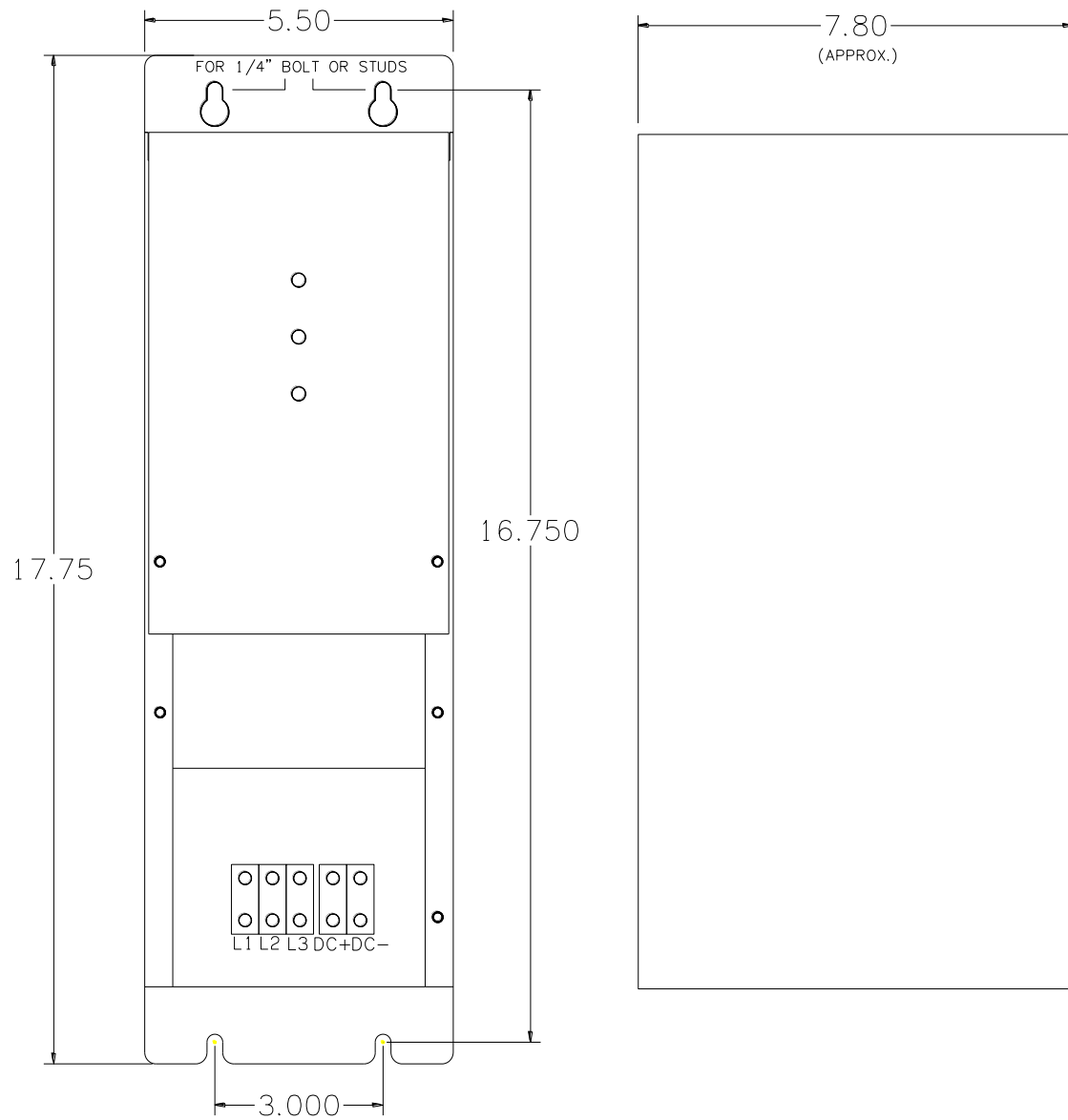


Figure 6-2: M3713SC K7 Chassis Dimensional Outline

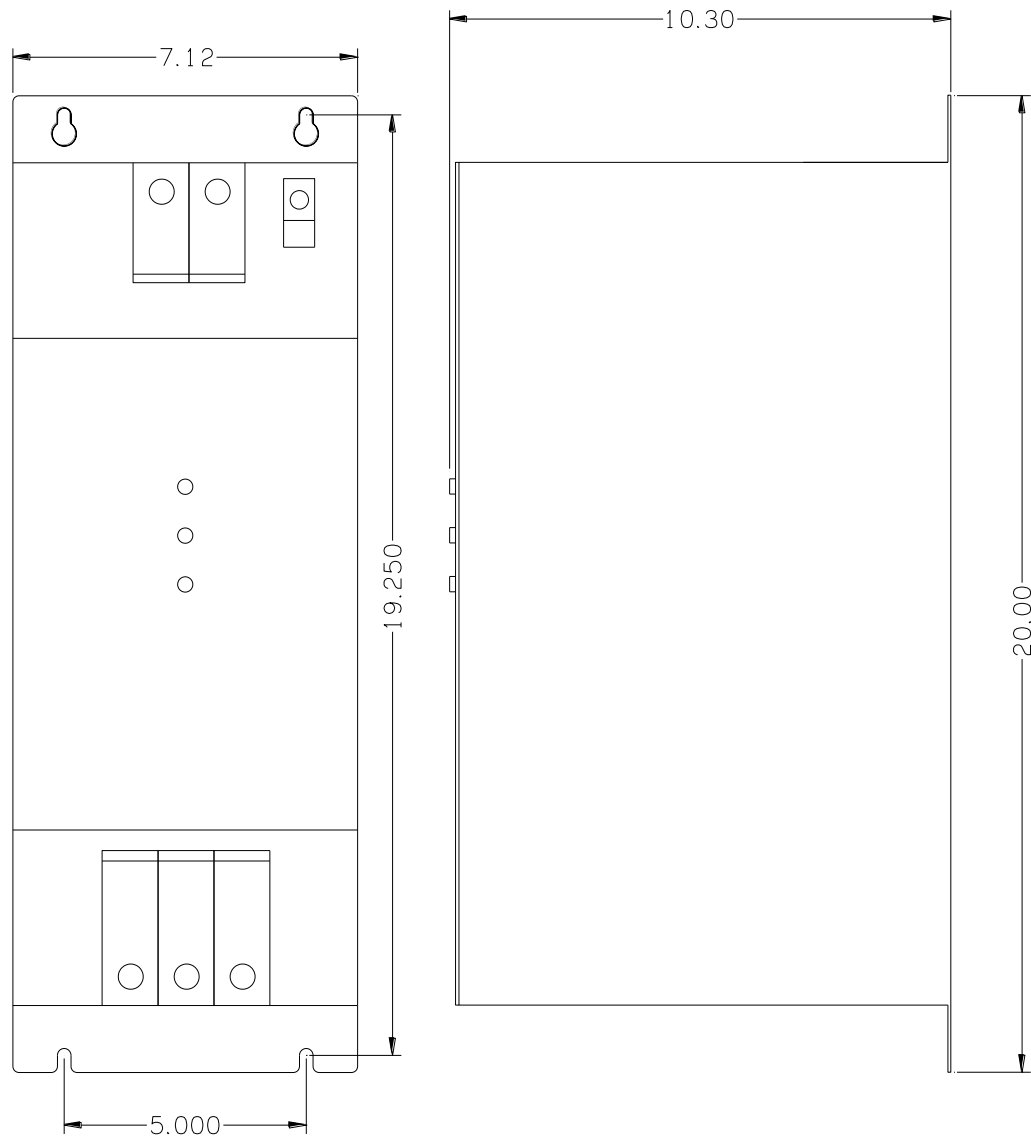
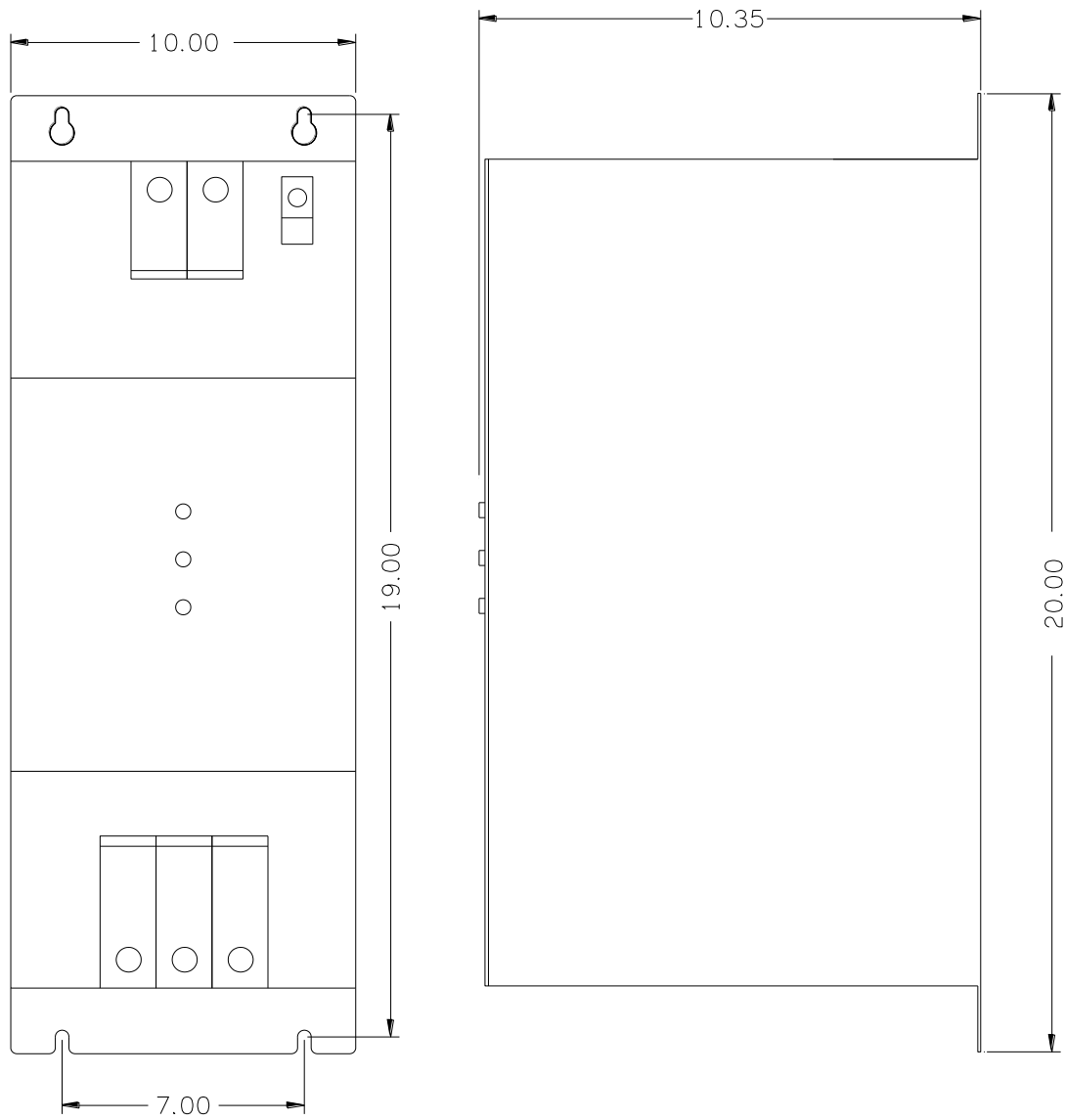


Figure 6-3: M3713SC K10 Chassis Dimensional Outline



6.5. BLOCK DIAGRAM

Figure 6-4: M3713SC Functional Block Diagram

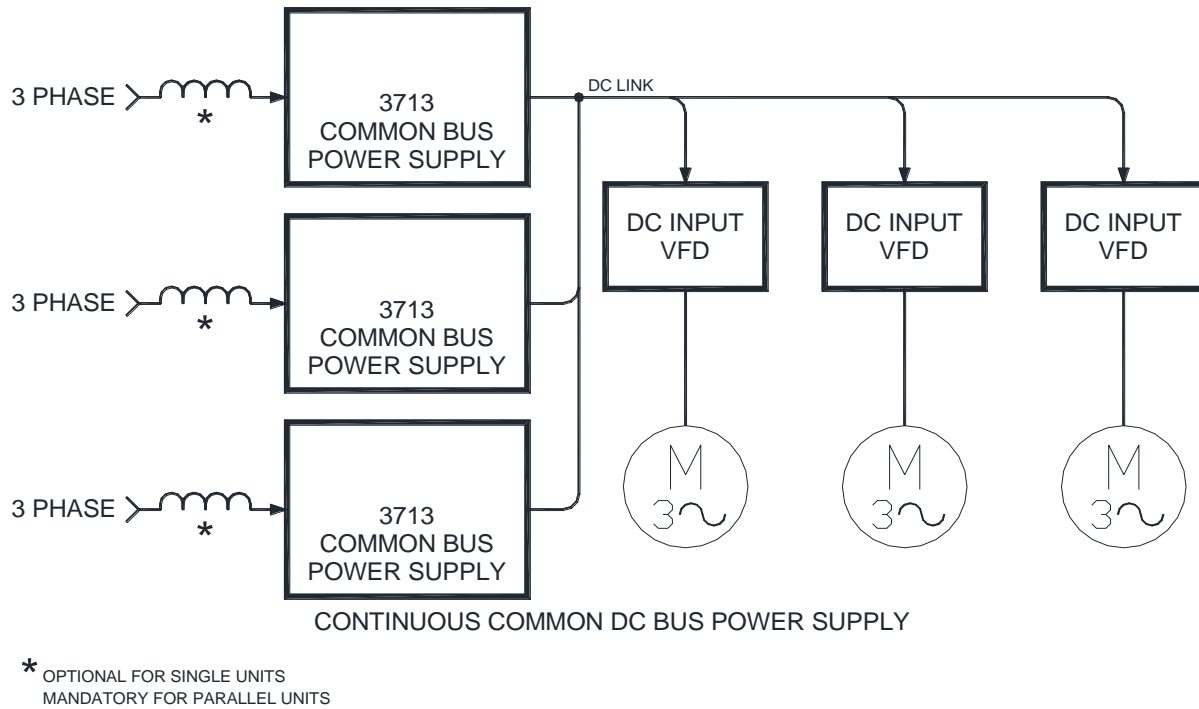
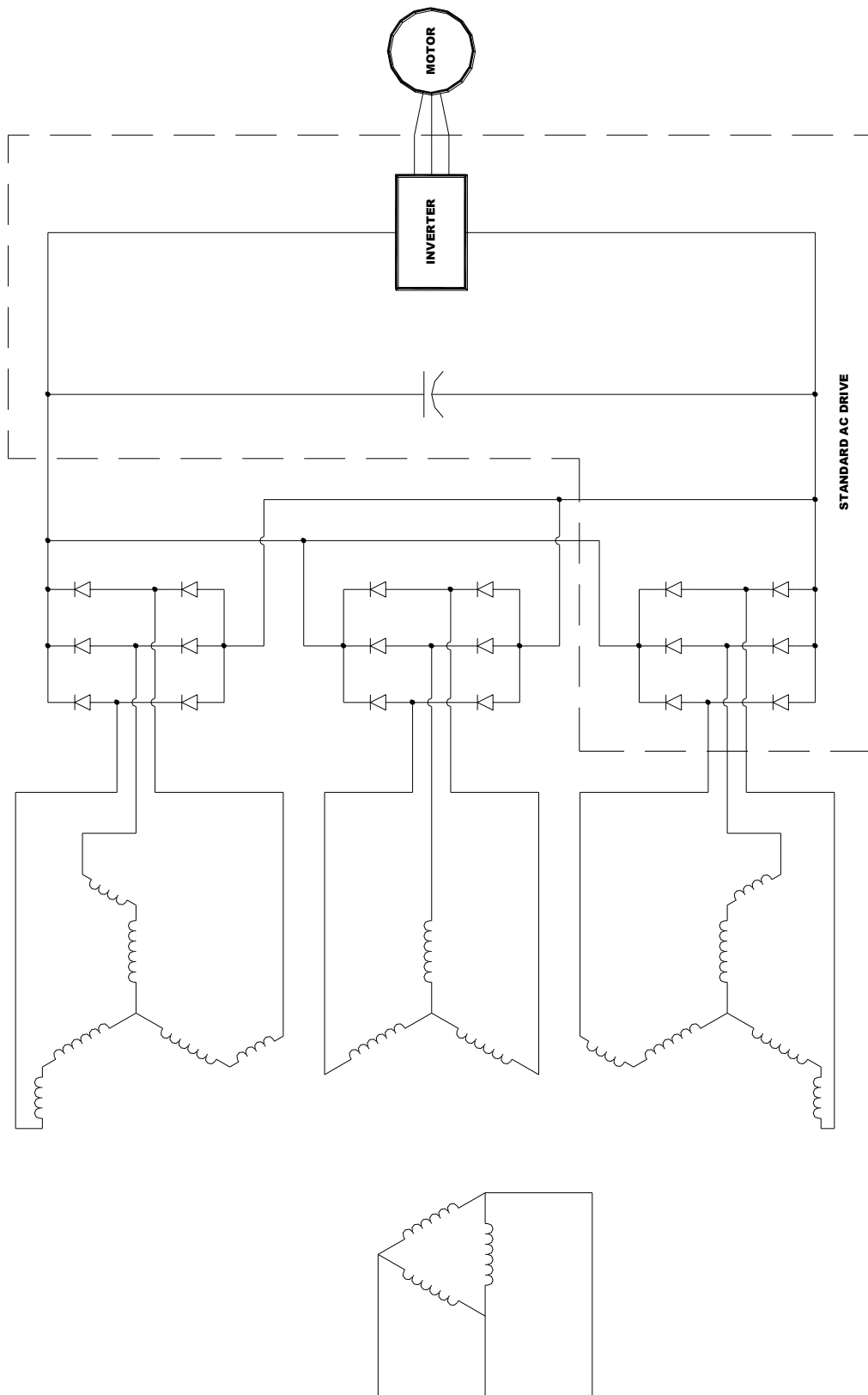


Figure 6-5: 18 Pulse Functional Block Diagram



7. APPLICATION NOTES

7.1. APPLICATION CONSIDERATIONS

The M3713SC is a 3-phase DC power supply. There are some issues that should be considered when designing the complete system.

7.1.1. DRIVES

Most variable frequency and servo drives are suitable for use with the M3713SC. Some things to consider are listed below.

Check the manual of the drive you are using, or call the technical support line for the drive manufacturer if you have questions on this hookup.

7.1.1.1. DC CONNECTION

The majority of variable frequency AC drives have a direct connection to the capacitor bank of the drive. This allows the M3713SC to precharge and run the drive directly through this connection, and should cause no problems with drive operation.

In general, the hookup can be described as a common bus input.

Check the manual of the drive you are using, or call the technical support line for the drive manufacturer if you have questions on this hookup.

7.1.1.2. DRIVES UNABLE TO BE POWERED FROM DC BUS

Due to connection points and certain topologies some drives may not be compatible with external DC supplies. The following drives do not support external DC supplies. Please consult drive manufacturer for details and support.

- Allen Bradley Powerflex 4 series
- Allen Bradley Powerflex 400-E frame.

7.1.1.3. ADDITIONAL CAPACITANCE

There must be a suitable amount of bus filter capacitance for each drive in the system. Many drives have these filter capacitors installed internally. If your drives do not have internal capacitance, additional capacitance may be included. Refer to your drive documentation for further information.

A rule of thumb is that there should be at least 40 μ F of capacitance per amp of supply, in other words, a 100 amp supply would need 4000 μ F of total capacitance to have acceptable ripple.

7.1.1.4. AC INPUT LOSS DETECTION

Some variable frequency AC drives incorporate AC input line sensing that causes a fault in the drive when the AC input lines are not used.

If the drive has phase loss detection, you can usually bypass this fault to allow the system to run without the AC input being connected.

7.1.1.5. 3-PHASE LOADS

A few large frame AC drives have 3-phase blower motors integral to the drive. If this is the case, the blower will not operate when the drive is powered from the M3713SC. This can cause overheating and drive faults or failure.

Some packaged drives may also have other 3-phase loads in the cabinets such as fans or power supplies.

If you have a drive that has an integral 3-phase motor, consult your drive manufacturer for a possible solution. One may be to install a small inverter or drive to power the 3-phase loads from the output of the M3713SC.

7.1.2. M3713SC PARALLEL POWER SUPPLIES

When placing the M3713SC in parallel with other power supplies, only use power supplies with the same model number.

Line reactors are required for each M3713SC when the units are placed in parallel, except for twelve and eighteen pulse systems that have a phase shifted transformer providing each rectifier with a separate AC input.

7.2. SYSTEM VOLTAGE AND SOURCE IMPEDANCE

The M3713SC is intended to be used with an input reactor for the reduction of peak input currents and bus ripple. The reactor adds inductive impedance to the circuit to reduce these factors, and adds to the total input impedance of the system. Other sources of inductive impedance in your installation are the main incoming transformer and the conductors to that transformer. If the total input impedance is too high, it can cause low voltage at the input of the M3713SC, and therefore the DC bus of the drive. This is referred to as a “soft” source, and will have a transformer closely matched to the load and high impedance.

7.2.1. TRANSFORMERS

Transformers are rated in kVA and percent impedance. In order to see what kVA your system needs, you can roughly multiply the horsepower by 1000. Your transformer should be rated higher than this. In other words, a 50 horsepower system would require at least a 50kVA transformer, if not larger. If the transformer has 5% impedance, the voltage drop to the output of the transformer at full load will be 5%. For instance, a transformer with 5% impedance and an open terminal voltage of 480VAC can have only 456VAC at the terminals at full load. If the transformer is much larger than the required kVA, or has a low percent impedance, the source is considered to be “stiff” and can cause high charging currents, high input harmonics, and system overheating.

If the input impedance is too high to the system, the input to the M3713SC can drop to the point where the DC bus of the drive will be out of specifications. When the DC bus falls too low, the motor can lose power or run hotter than usual. If the DC bus falls low enough, the drive will trip and not operate the motor. This typically is shown as an undervoltage fault on the drive.

7.2.2. INPUT REACTORS

Input reactors are used for many reasons, all of which are related. Input reactors reduce the peak input currents to the power supply and provide some protection from incoming spikes and surges.

When using parallel power supplies, input reactors must be used to ensure current sharing between the inputs. This does not apply to twelve or eighteen pulse installations because the rectifiers are not in parallel as each rectifier has a separate phase-shifted AC feed.

A minimum of 3% impedance should be used along with a derating of 10% for the combined power supply capacity.

The impedance of the reactor reduces the RMS input currents, which can reduce nuisance tripping of incoming overload protection devices. The bus voltage ripple is also reduced, which causes less capacitor heating and therefore increases capacitor lifespan.

Input reactors are generally rated for RMS current and percentage, much as transformers are rated. If the reactor has 5% impedance, the voltage drop to the output of the reactor at full load will be 5%. For instance, a 480V reactor with 5% impedance can only have 456VAC at the terminals at full load.

If the total input impedance is too high to the system, the input to the M3713SC can drop to the point where the DC bus of the drive will be out of specifications. When the DC bus falls too low, the motor can lose power or run hotter than usual. If the DC bus falls low enough, the drive will trip and not operate the motor. This typically is shown as an undervoltage fault on the drive.

7.3. INPUT VOLTAGE IMBALANCE

The balance between phases on the input of a 3-phase system can be critical. Depending on input impedances, a voltage imbalance of as little as 3% can cause the 3-phase bridge to effectively operate as a single phase bridge. This causes high input currents and capacitor overheating.

Isolation transformers can be used to mitigate voltage imbalances seen from the incoming supplies.

7.4. SIZING 12 OR 18 PULSE SYSTEMS

When choosing which M3713SC power supplies to use in 12 or 18 pulse systems, the design is governed by the size of the motor and the VFD. The VFD's inverter section must be sized to handle the load power. However, because the total load current is being supplied through several rectifying front ends the M3713SC does not have to be sized to handle the full load current.

If the rectifier section of the VFD is being utilized, then only a single M3713SC power supply is required for 12 pulse systems (See Figure 3-5). While two M3713SC power supplies are required for 18 pulse systems (See Figure 3-6).

If the VFD does not have a rectifier front end or is not being utilized in order to create a common DC bus, then two M3713SC power supplies are required for 12 pulse systems (See Figure 3-7). While three M3713SC power supplies are required for 18 pulse systems (See Figure 3-8).

For Figures 3-5 and 3-6 for the layout of the aforementioned 12-pulse systems, the two M3713SC power supplies should be sized to 75% of the full load current in 12-pulse systems.

For Figures 3-7 and 3-8 for the layout of the aforementioned 18-pulse systems, the three M3713SC power supplies should be sized to 50% of the full load current in 18-pulse systems.

7.5. M3713SC WITH CAPACITOR BANK

During a braking event, a variable frequency drive pulls mechanical energy out of the motor into the drive's capacitor bus. This additional energy causes the DC bus voltage to rise, which can eventually cause the drive to shut down. With a line regen this energy can be returned to the AC line; however, sometimes line regeneration is not possible due to constraints on the AC source. Braking transistors are another option, but at the cost of increased energy consumption.

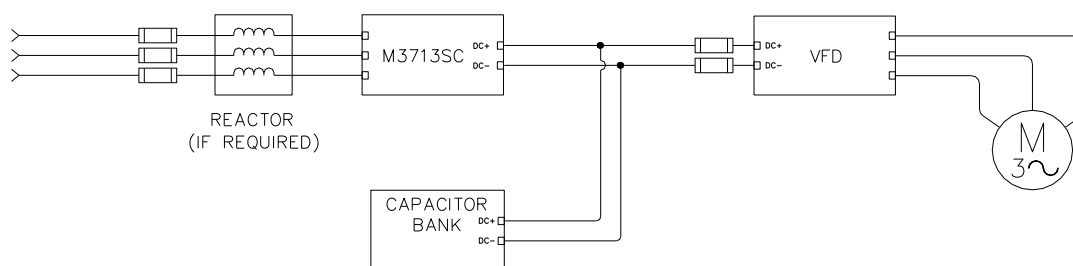
Bonitron provides an economical solution to cyclical braking situations where line regen is unavailable by adding capacitance to increase the capacitance of their drive bus, proportionally reducing the rate of voltage rise. Braking energy can now be stored directly on the DC bus, to be reused during the next motoring cycle. The additional capacitance can also increase the drive's operational time during line sags or outages. In cases where safety discharge is required, Bonitron offers KIT 3628T and M3628R to safely discharge the capacitor bank to a safe level.

Since most VFDs can only precharge a limited amount of drive capacitance, M3713SC can be used to supply power to the entire drive system. This completely eliminates the possibility of damage to the drive's internal rectifier. For operation with a large capacitor bank, the M3713SC must be ordered with the NORL option.

To reduce harmonics, a 5% line reactor is recommended.

Single-phase operations are also possible, eliminating the need to oversize the VFD. Contact Bonitron for details on this option.

Figure 7-1: M3713SC with Capacitor Bank



To Size the Required Capacitance

To size the required capacitance, the AC line voltage and the maximum allowed DC bus voltage must be known. If there is a braking transistor in the system, its setpoint determines the maximum DC bus voltage at which the capacitors will save energy.

- For a 230 VAC systems the maximum DC bus voltage with a braking transistor is typically 375 VDC.
- For a 460 VAC systems the maximum DC bus voltage with a braking transistor is typically 750 VDC.

Once the V_{min} value is known, you can calculate the minimum capacitance required.

Calculating C_{min}

If the average braking time and average braking current are known use the following equation:

$$C_{min} = \frac{I_{avg} t_{brake}}{(V_{max} - \sqrt{2}V_{line})}$$

If you know the braking energy in Joules use the following equation:

$$C_{min} = \frac{2E_{brake}}{(V_{max}^2 - 2V_{line}^2)}$$

If the average braking current or the braking energy is not known, use the braking power, in horse power, to get an estimate of the required energy by using the following equation:

$$C_{min} = \frac{2(P_{brake} * 746 \frac{W}{HP} * t_{brake})}{(V_{max}^2 - 2V_{line}^2)}$$

Once the value for C_{min} is known, Bonitron can help you identify and source the most cost-effective capacitor bank to meet your needs.

Calculating Savings Per Year

Calculating total savings per year in dollars:

$$S_{year} = \frac{(8.76)E_{brake}P_{kWh}D}{t_{cycle}}$$

Where

S_{year} is dollars saved per year.

8.76 is seconds per year multiplied with conversion of Joules to kWh.

E_{brake} is the braking energy.

P_{kWh} is the cost in dollars per kilowatt-hour.

D is the duty cycle, which is percentage of time the system is braking during a cycle.

t_{cycle} is the time in seconds to complete a cycle.

Calculating Ride-Thru Time

You can compute the extended ride-thru capability that has been created by the added capacitance.

One must know the load horsepower, the minimum nominal AC line voltage, and the minimum DC bus voltage acceptable by the drive.

- For a 230 VAC systems the minimum DC bus voltage where a drive can still operate is typically 200 VDC.
- For a 460 VAC systems the minimum DC bus voltage where a drive can still operate is typically 400 VDC.

To find the additional ride-thru time in seconds use the following equation:

$$t_{ridethru} = \frac{C(2V_{line}^2 - V_{min}^2)}{2(746 \frac{W}{HP} * P_{load})}$$

If more ride-thru time is desired, a larger capacitance can be added to the DC bus.

Example Capacitance Sizing

In this example, the line voltage is 480 VAC, the braking energy is 1kJ for four seconds, total cycle time is 8 seconds, the cost is \$.10/kWh

$$C_{min} = \frac{2(1kJ)}{(750VDC^2 - 2(480VAC^2))} = 0.0393F$$

Rounding up to the nearest common value gives 40,000 μ F or 0.04F of capacitance.
To calculate the resulting savings:

$$S_{year} = \frac{(8.76)(1kJ)(.10\frac{\$}{kWh})(.50)}{8s} = \$54.75$$

To calculate the added ride-thru time if the load horse power is 10 HP.

$$t_{ridethru} = \frac{(0.04F)(2(480VAC)^2 - 400VDC^2)}{2(746\frac{W}{HP} * 10HP)} = 0.8s$$

INTERVIEW

This image shows a single sheet of white paper with horizontal ruling lines. The lines are evenly spaced and run across the width of the page. There are no margins, text, or other markings on the paper.

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